Basic Usage of New GPIO Test Program

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Document History			
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Version 1.2	16 January 2016	New document describing usage of new-gpiotest program with GPIO irq capabilities	

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1. Background

new-gpiotest is alternative C++ program used to access the Omega GPIO pins.

While it has some similarities to **fast-gpio** it has extended capabilities including usage of interrupts on the GPIO pins.

It consists of two main components:

- libnew-gpio.so a dynamic library containing the classes used to interact with GPIO pins
- new-gpiotest a simple test program for interacting with GPIO pins using libnew-gpio.so

Full details of the library, the program and all source code can be found at <u>Alternative C++ Code for GPIO Access</u> (https://community.onion.io/topic/143/alternative-c-code-for-gpio-access)

This document primarily outlines the basic usage of the new-gpiotest program.

2. Pre-requisites

To use the **new-gpiotest** program, your Omega **must** fulfil the following pre-requisites:

- Must have been upgraded to version 0.0.6-b265 or later
- Must have the kmod-gpio-irq package installed by running:

opkg update opkg install kmod-gpio-irq

3. Files Supplied

There are two files required for new-gpiotest:

- libnew-gpio.so the required dynamic library
- new-gpiotest the program itself

4. Basic Installation

Installing the software is simple. It primarily consists of copying the library and test program to suitable locations on your Omega.

4.1. Installing libnew-gpio.so

Copy the **libnew-gpio.so** file to the **/lib** directory on your Omega.

Alternatively, you can copy the library to any location that may be set up in any **LD_LIBRARY_PATH** directory on your Omega. For example, I use the following for testing:

- Created directory /root/lib
- Copied the library to /root/lib
- Added the following lines to my /etc/profile file:

LD_LIBRARY_PATH=/root/lib:\$LD_LIBRARY_PATH export LD_LIBRARY_PATH

4.2. Installing the new-gpiotest Program

Copy the **new-gpiotest** program file to any suitable directory on your Omega from which you wish to run it.

5. Usage of the new-gpiotest Program

The **new-gpiotest** program accepts a set of parameters to control its operation.

The program will document it's usage when the command **new-gpiotest help** is used.

In addition, the usage is shown whenever any errors are detected in the parameters.

The usage information displayed is:

```
./new-gpiotest
Usage
Commands - one of:
         - ./new-gpiotest <op> <pin> <val>
        - ./new-gpiotest pwm <pin> <freq> <duty>
                 Starts PWM output on pin
        - ./new-gpiotest pwmstop <pin>
                 Stops PWM output on pin
        - ./new-gpiotest irq <pin> <irqtype> <irqcmd> <debounce>
                 Enables IRQ handling on pin
        - ./new-gpiotest irqstop <pin>
                 Terminates IRQ handling on pin
Where:
        <op> is one of:
                 info - to display info on pin(s)
                 set - to set pin(s) value
                 get - to get and return pin value
                 setd - to set pin(s) direction
                 getd - to get and return pin direction
                 help - to display usage
        <pin> is one of
                0, 1, 6, 7, 8, 12, 13, 14, 15, 16, 17, 18, 19, 23, 26, all A <pin> of all can only be used for an <op> of:
                         info, set, setd
        <val> is only required for set and setd:
                 for set, <val> is 0 or 1
                 for setd, <val> is in or out
        <freq> is PWM frequency in Hz > 0
        <duty> is PWM duty cycle % in range 0 to 100
        <irqtype> is the type for IRQ and is one of:
                falling, rising, both
        <irqcmd> is the shell command to be executed when the IRQ occurs
                 Must be enclosed in " characters if it contains
                 spaces or other special characters
                 If it starts with the string [debug],
                debug output is displayed first
        <debounce> is optional debounce time for IRQ in milliseconds
                 Defaults to 0 if not supplied
```

Notes:

- 1. The return value from the command will be one of the following:
 - **255 (-1)** indicates an error has occurred either in the parameters or in executing the command
 - 0 indicates normal successfully completion for an operation (<op>) other than get or getd
 - For a successful **get** operation:
 - o **0** indicates the pin is **off**
 - o 1 indicates the pin is on
 - For a successful **getd** operation:
 - o **0** indicates the pin is an **input** pin
 - o 1 indicates the pin is an output pin
- 2. When the **pwm** operation is used, the program forks a separate process to perform the PWM output.

This separate process continues after the program returns until such time as the **pwmstop** operation is performed on the same pin.

The ID of the separate process can be discovered by running:

new-gpiotest info <pin-number>

3. When the **irq** operation is used, the program forks a separate process to monitor and respond to pin state changes.

Each time the relevant pin undergoes the relevant change in state, the **<irqcmd>** command specified is run.

This separate process continues after the program returns until such time as the **irqstop** operation is performed on the same pin.

The ID of the separate process can be discovered by running:

new-gpiotest info <pin-number>